



Energetic Macroscopic Representation for control of energy conversion systems

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Energy Conversion Systems



Energy Conversion Systems

manipulation of energy
with losses, delays,
and safety issues!

Interconnected subsystems
organized for a common goal
in interaction with an environment



Sustainable development:

- more electrified vehicles
- more renewable energy
- more efficient systems
- etc.



High-quality energy
conversion systems

How to develop efficient control of energy conversion systems?

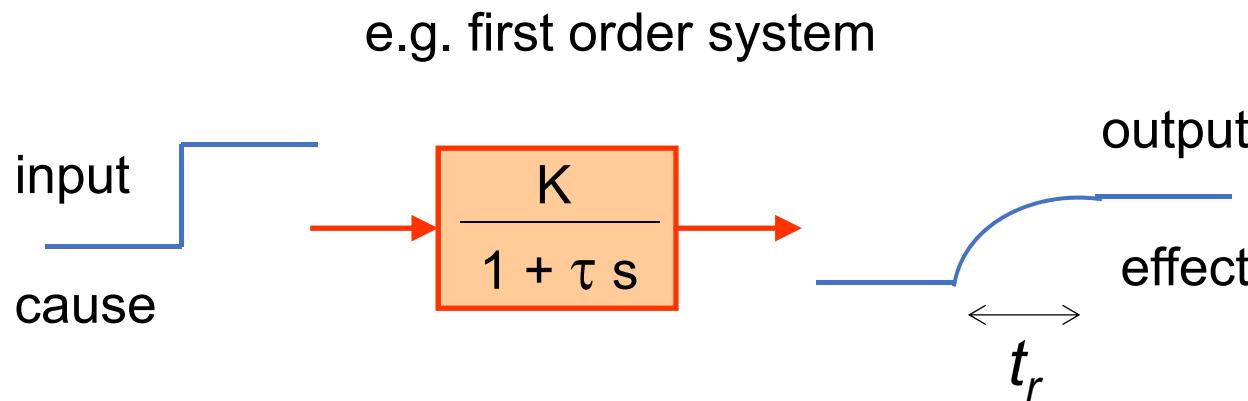
Causality principle

the cause leads to the effect

i.e. the output is delayed from the input

i.e. the output is an integral function of the input

i.e. the model describes an energy storage

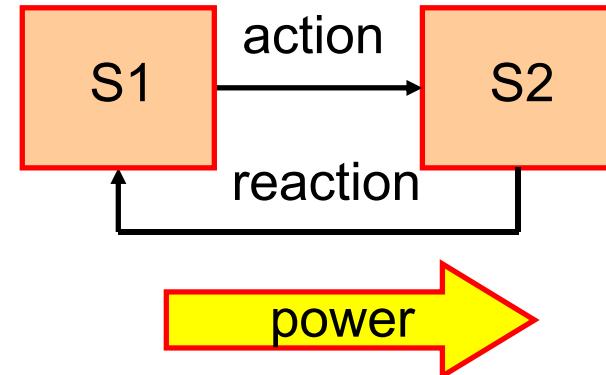


an input change leads to
an output change **with a delay**

Only integral relationships are causal
(physical behaviour, better understanding, safer management)

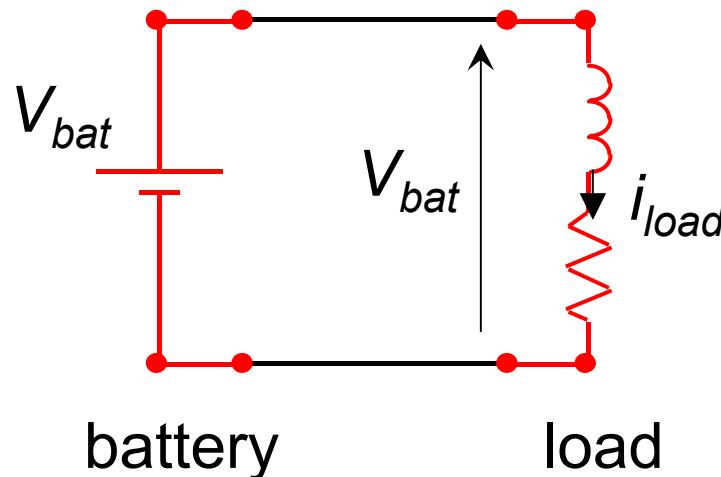
Interaction principle

Any action induces a reaction

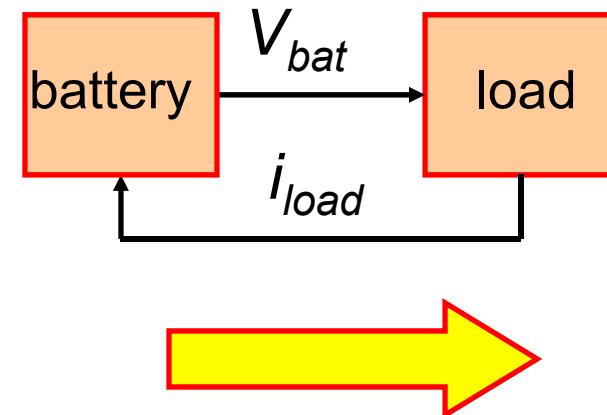


$$\text{Power} = \text{action} \times \text{reaction}$$

Example: battery and load

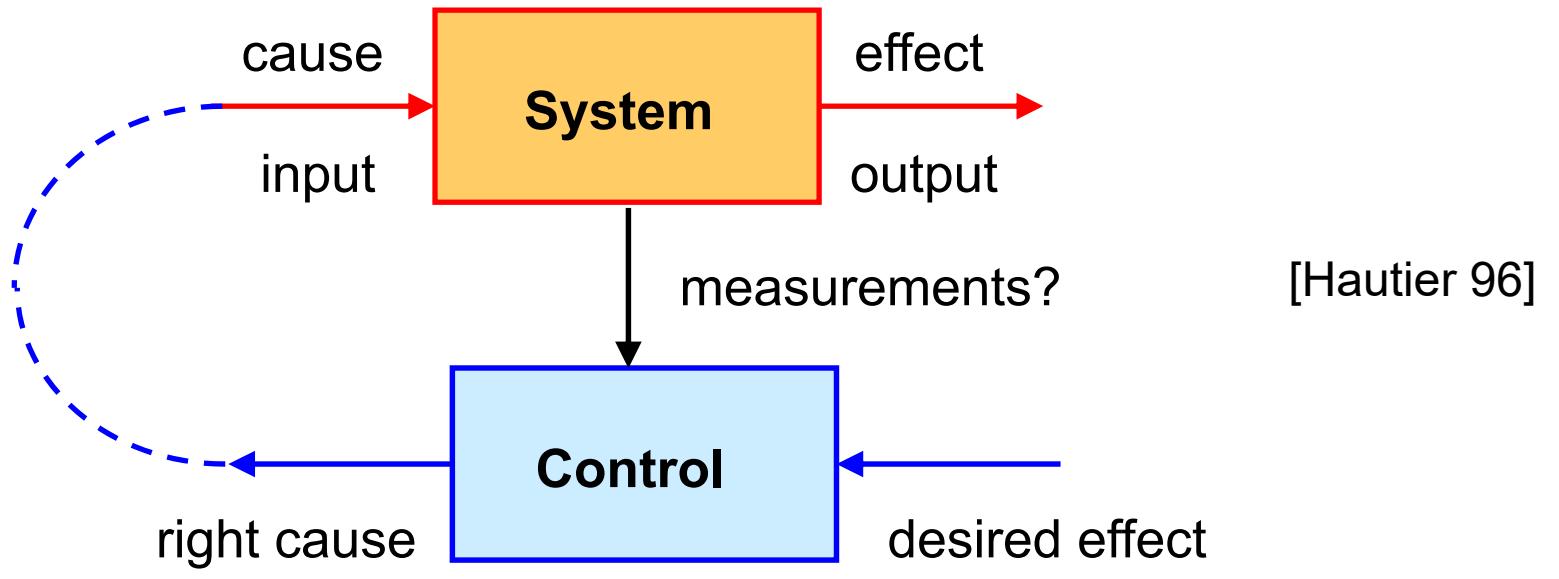


[Bouscayrol 2000]



$$P(t) = V_{bat}(t)i_{load}(t)$$

Inversion principle



control = inversion of the causal path

How to organize the control of innovative energy conversion systems?



Energetic Macroscopic Representation (EMR)

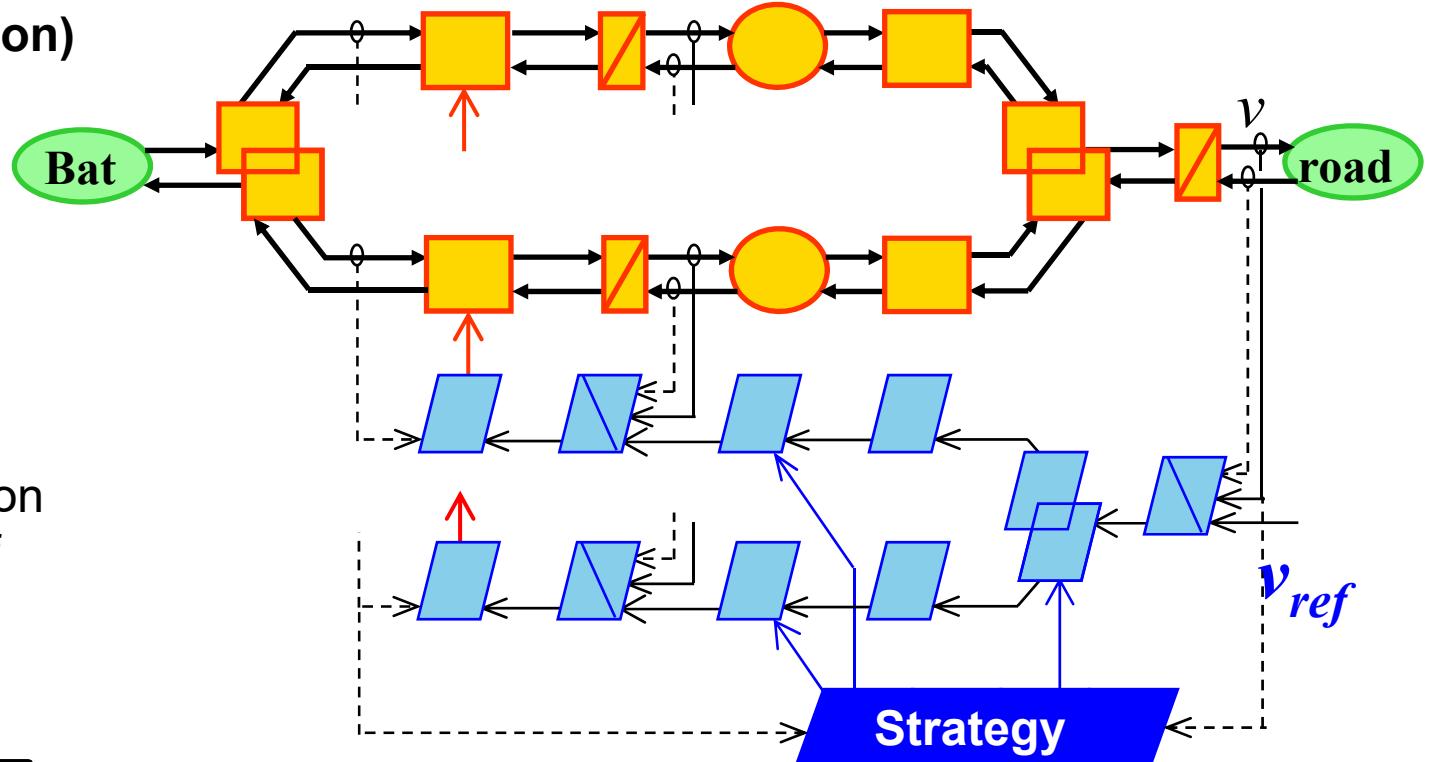
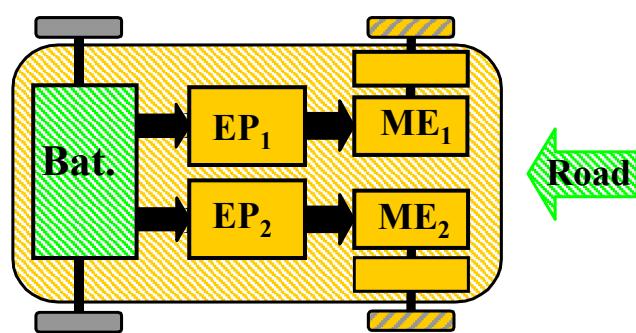


What is EMR?

EMR
(graphical description)

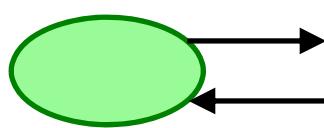
=
organization
of models of
complex systems

Systematic deduction
of organization of
control schemes

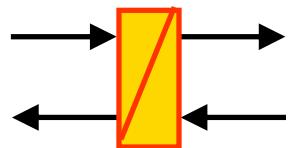


EMR pictograms

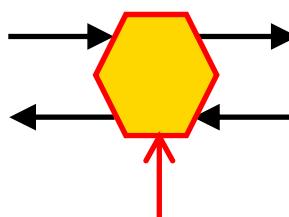
Only 4 energy functions are OK to describe energy conversion systems



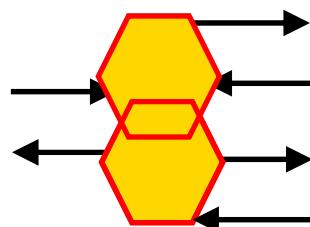
Energy source



Energy accumulation



Energy conversion
(potential tuning)

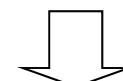


Energy distribution

all elements connected
by action/ reaction (Systemics)

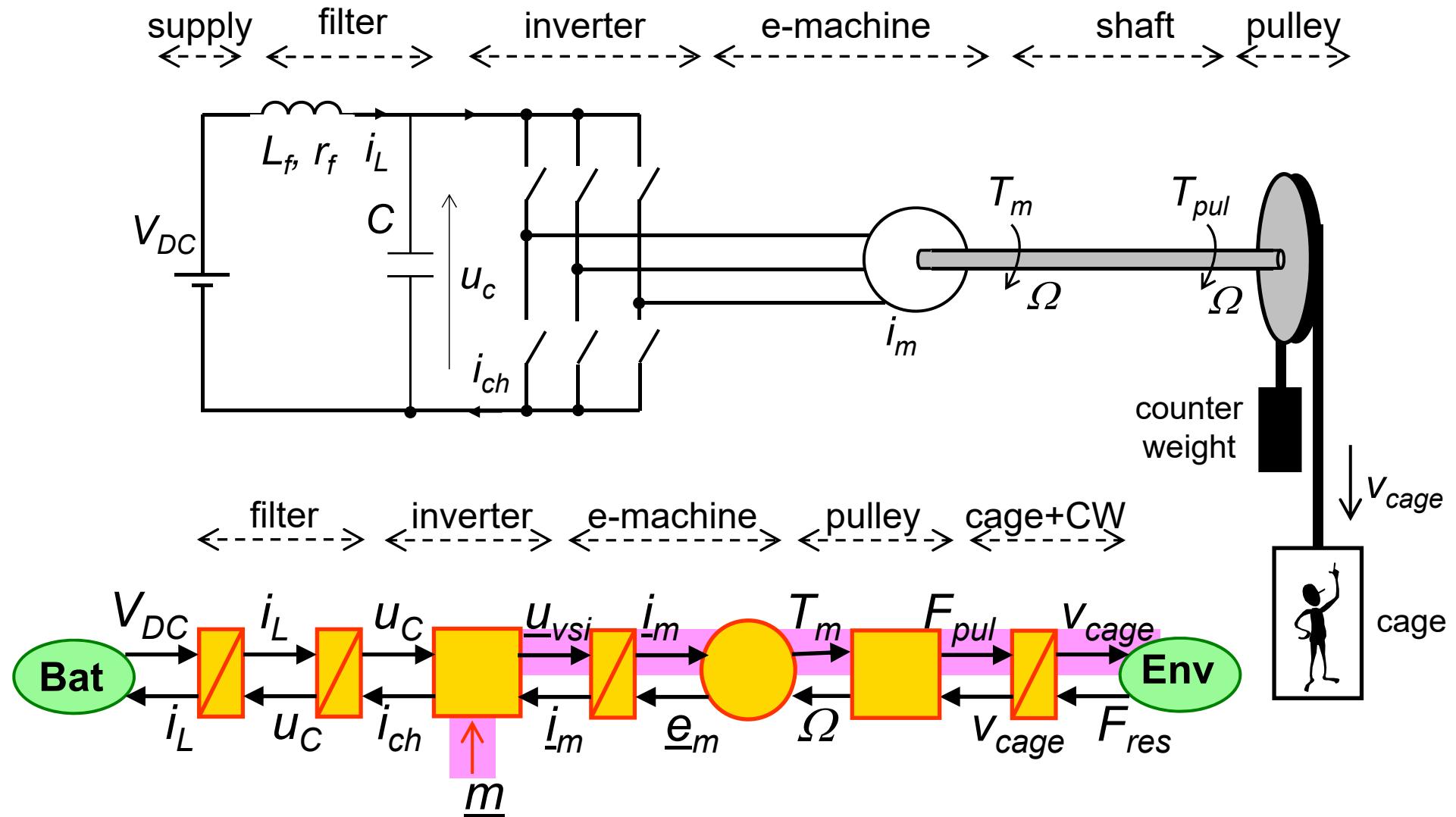
all power I/O defined
by accumulation elements
(causality)

only conversion elements
can have tuning inputs

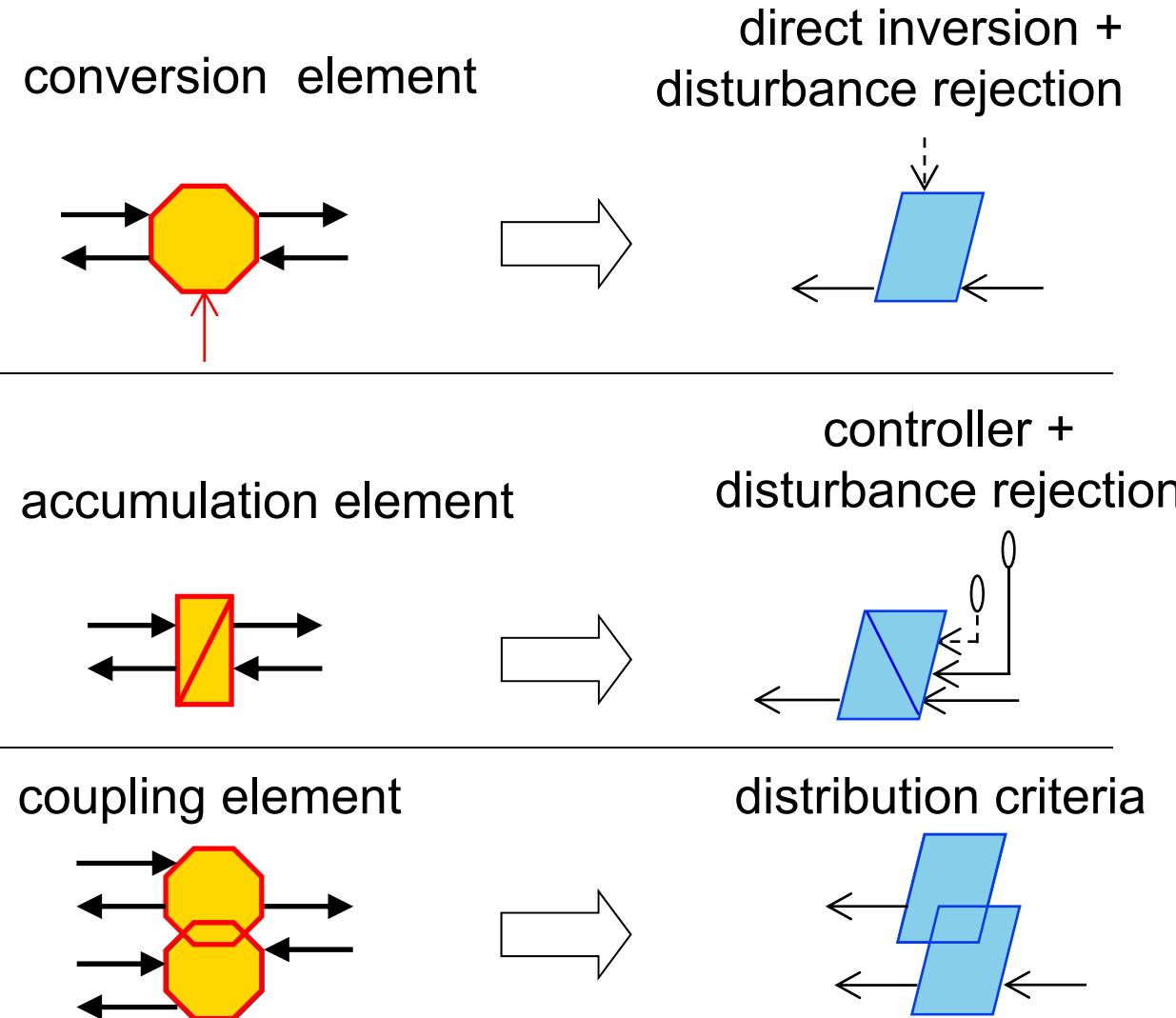


valuable for control design

EMR of a lift system

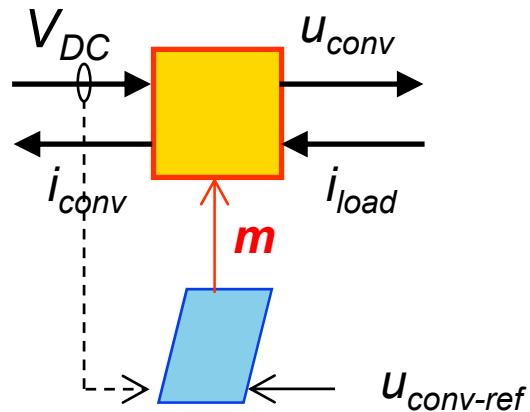


Control of EMR elements



Example of inversions

DC/DC converter

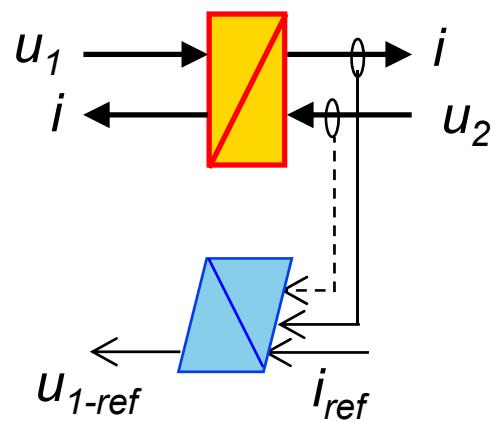


$$\begin{cases} u_{conv} = m \cdot V_{DC} \\ i_{conv} = m \cdot i_{load} \end{cases}$$

direct
inversion

$$m = u_{conv-ref} / V_{DC-mes}$$

inductor



$$u = ri + L \frac{di}{dt} + u_2$$

closed-loop
control

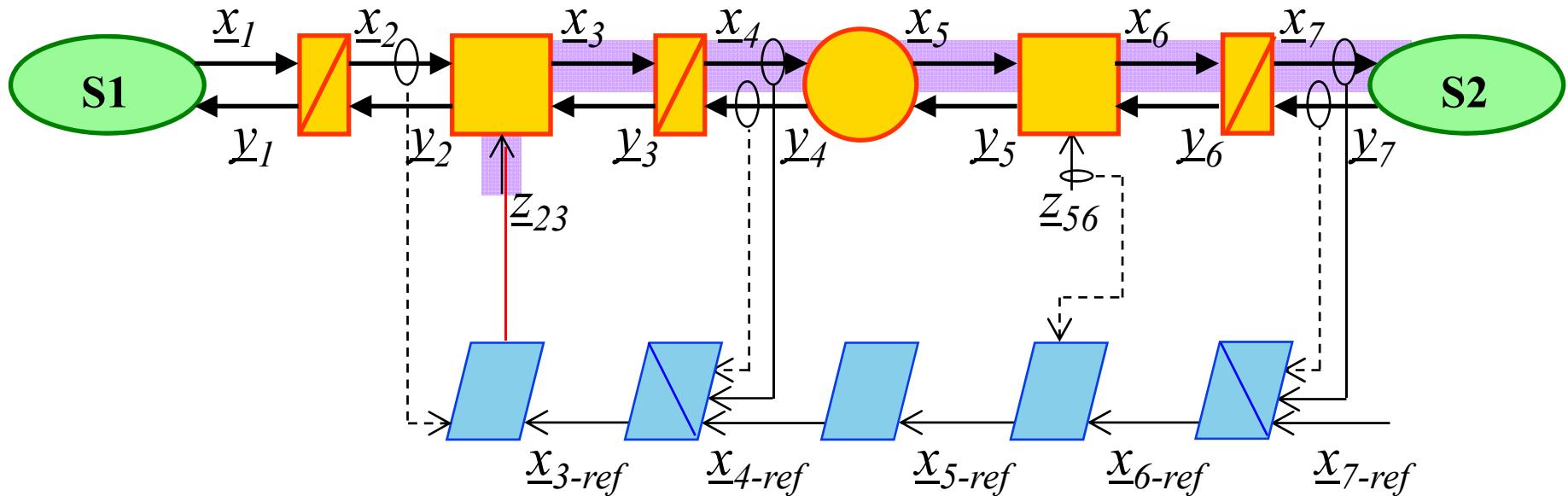
$$u_{1-ref} = C(t) (i_{ref} - i_{mes}) + u_{2-mes}$$

Control scheme deduction (maximal)

1. EMR of the system

2. Tuning path

3. Inversion step-by-step Strong assumption: all variables can be measured!



Maximal Control Structure (or scheme):

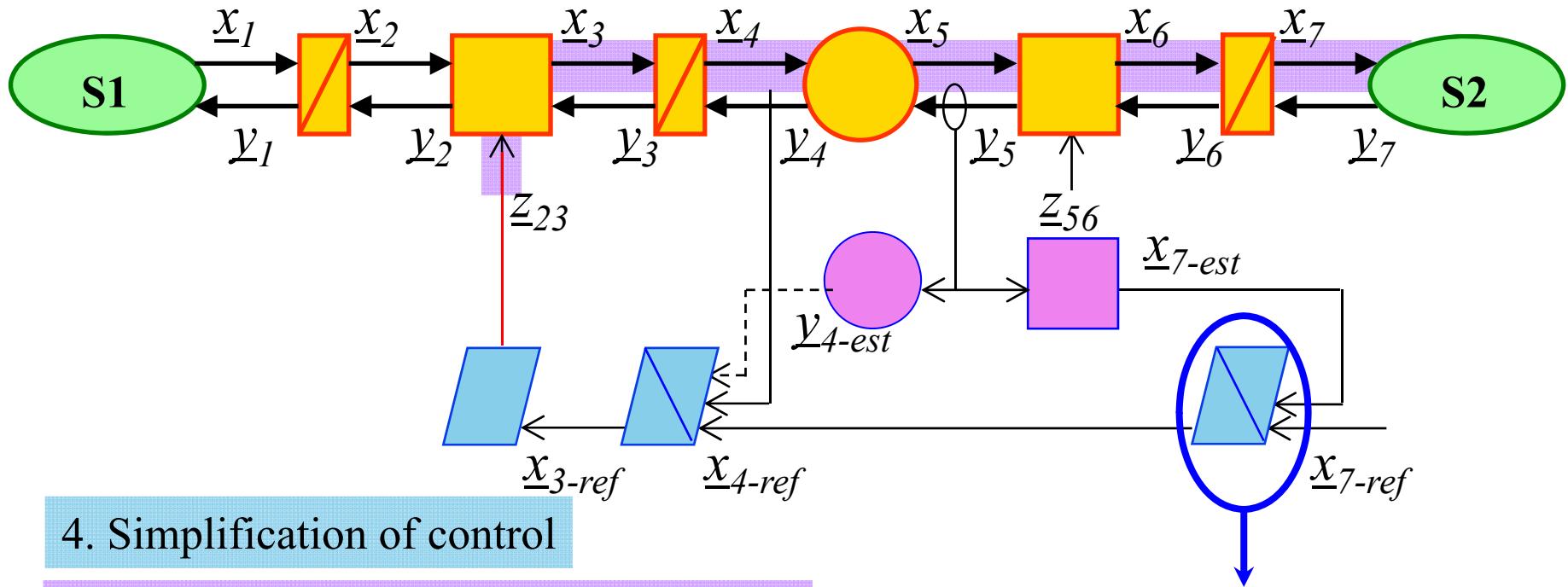
- maximum of sensors
- maximum of operations

Control scheme deduction (practical)

1. EMR of the system

2. Tuning path

3. Inversion step-by-step Strong assumption: all variables can be measured!



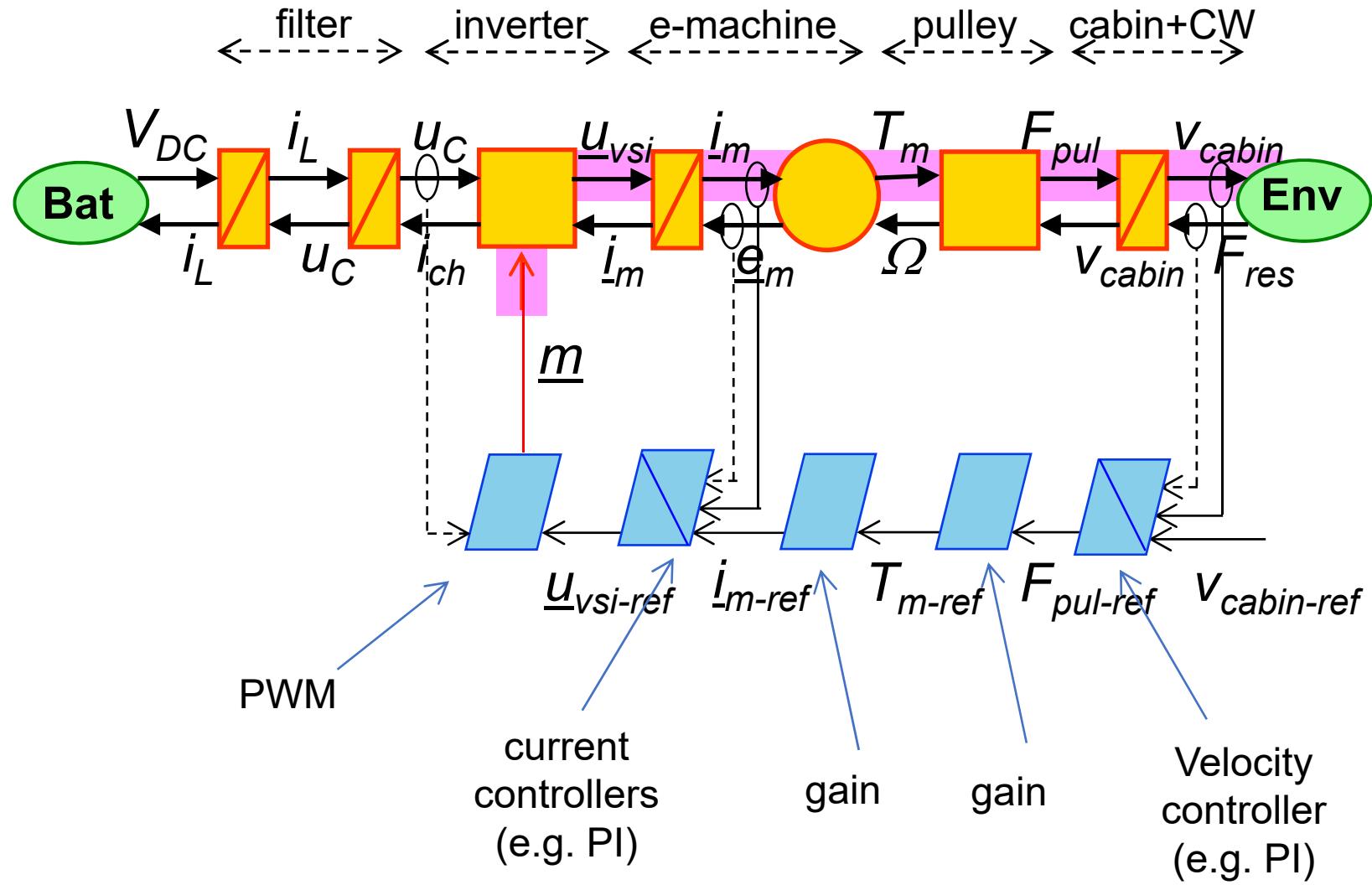
4. Simplification of control

5. Estimation of non-measured variables

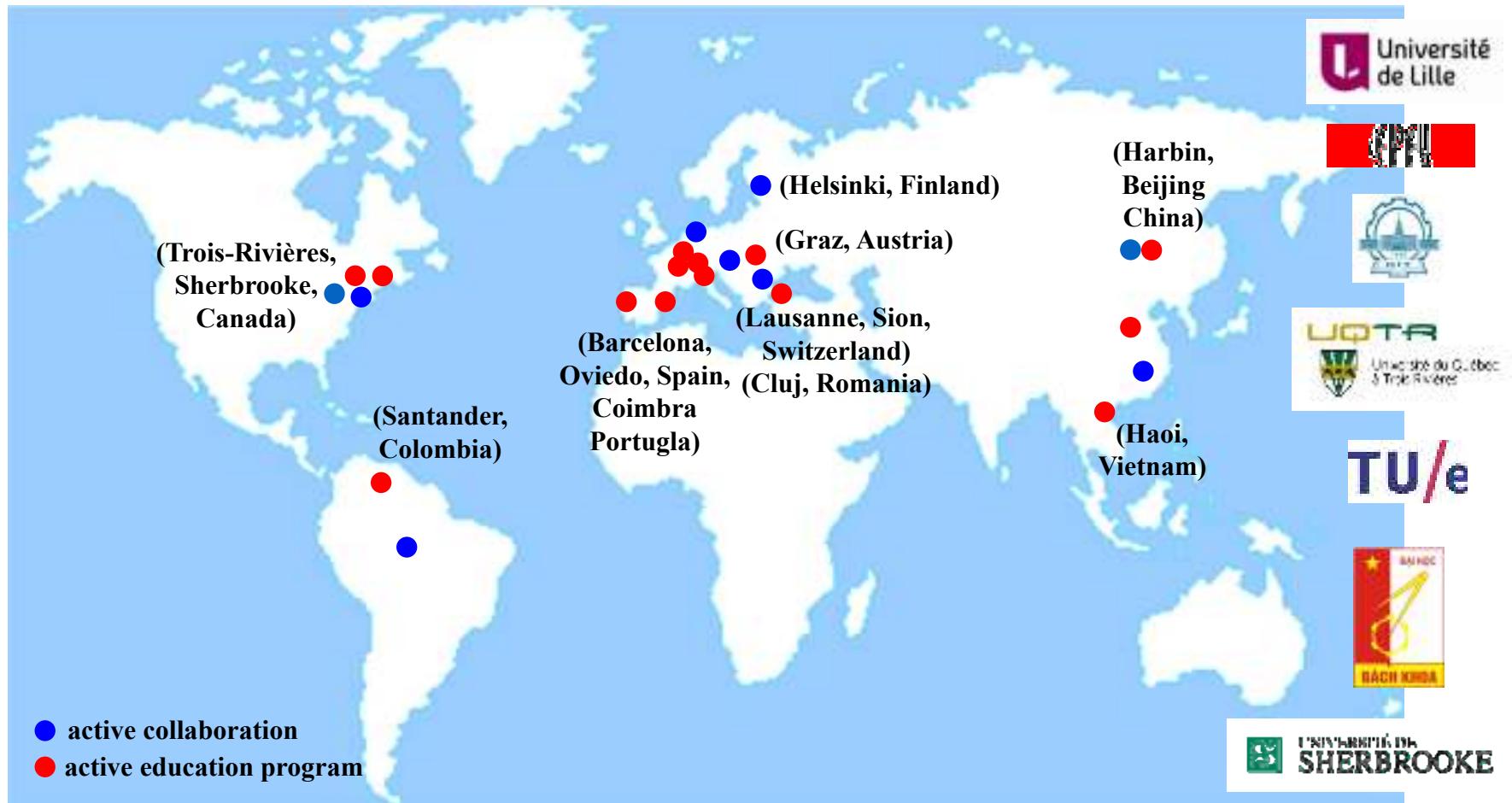
6. Tuning of controllers

PI / PID / fuzzy controller?
Calculation of parameters?

Control of the lift system



EMR & dissemination



Industry





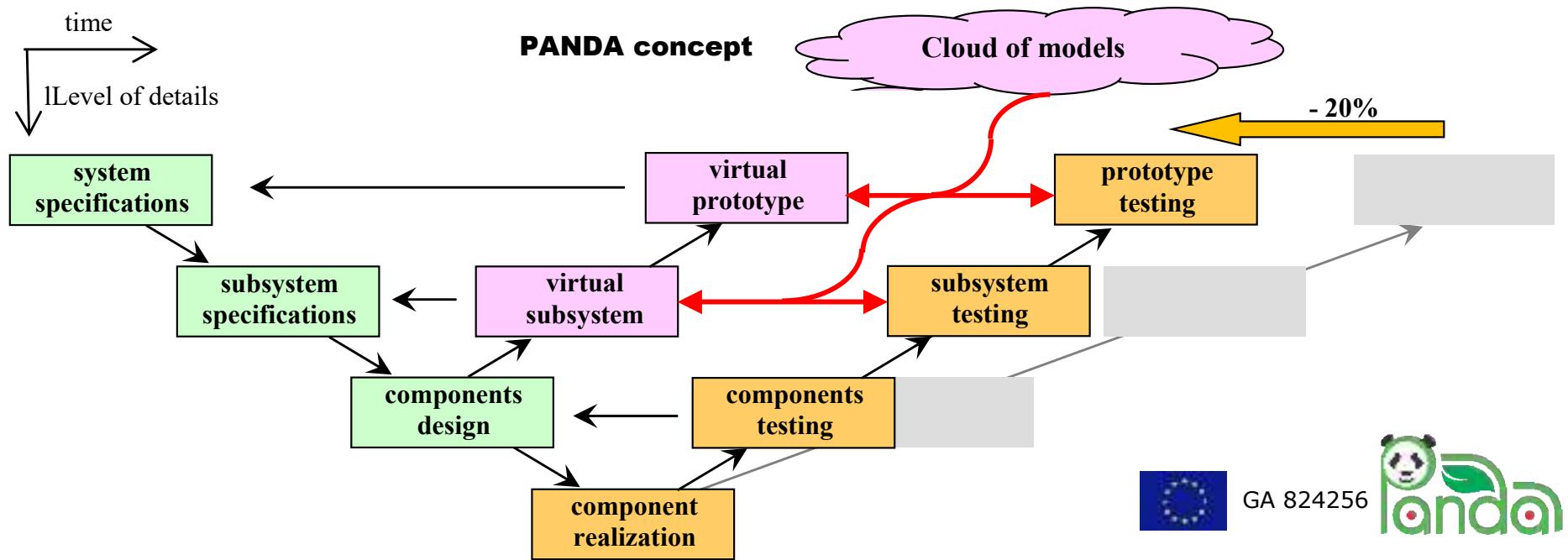
Application to the H2020 PANDA project



H2020 PANDA



Powerful Advanced N-level Digital Architecture for models of EVs and components



Université
de Lille



SIEMENS
Valeo



Typhoon HIL



UBFC
UNIVERSITÉ
FRANÇAISE
FRANCHE-COMTÉ

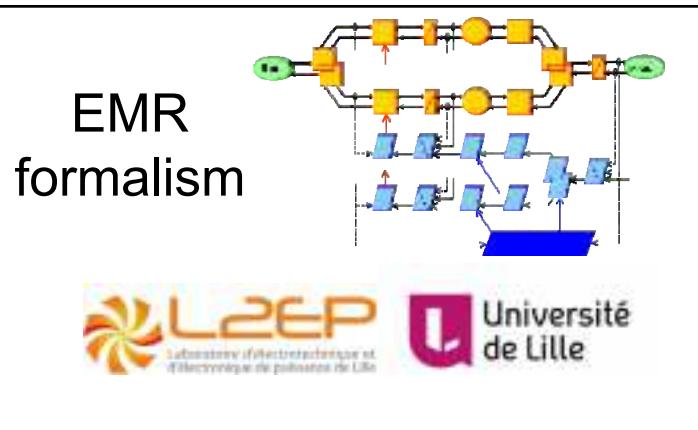


RENAULT

ELLIWAYS

Unified model organization for virtual and real testing
of electrified vehicles (**using EMR**)

PANDA developments



Application to an industrial software



study cases

The EMR of the studied BEV



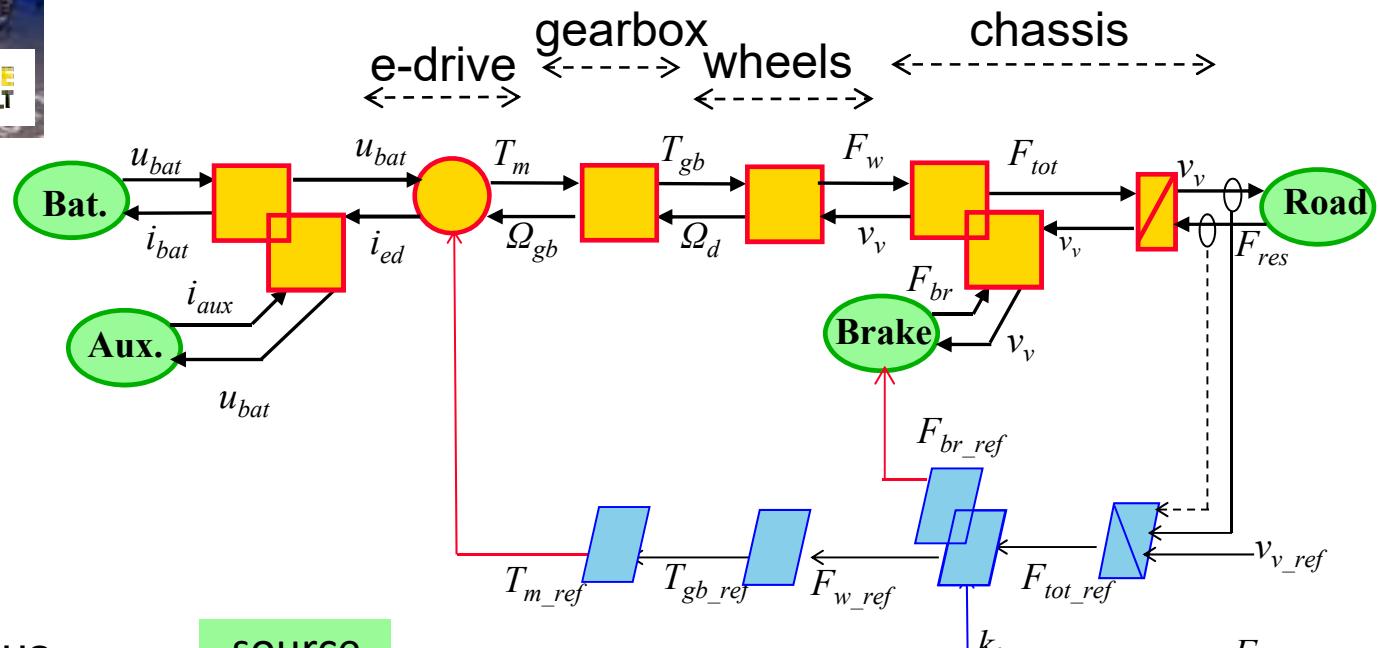
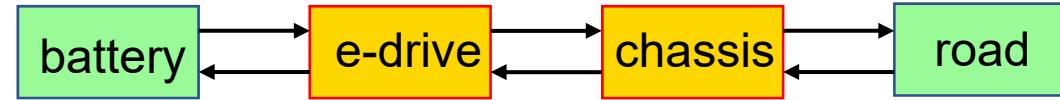
Renault ZOE



Li-ion
41 kWh
400 V
290 kg

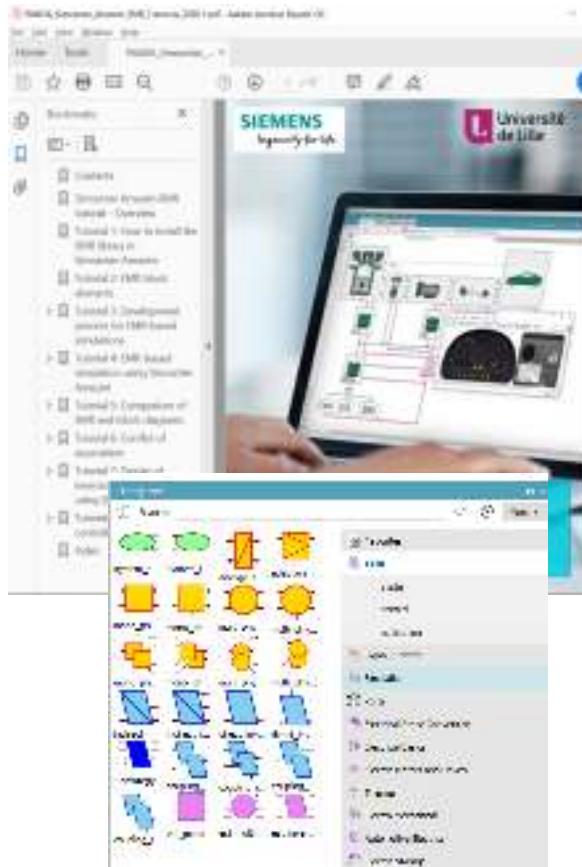


Synchronous
Machine
65 kW

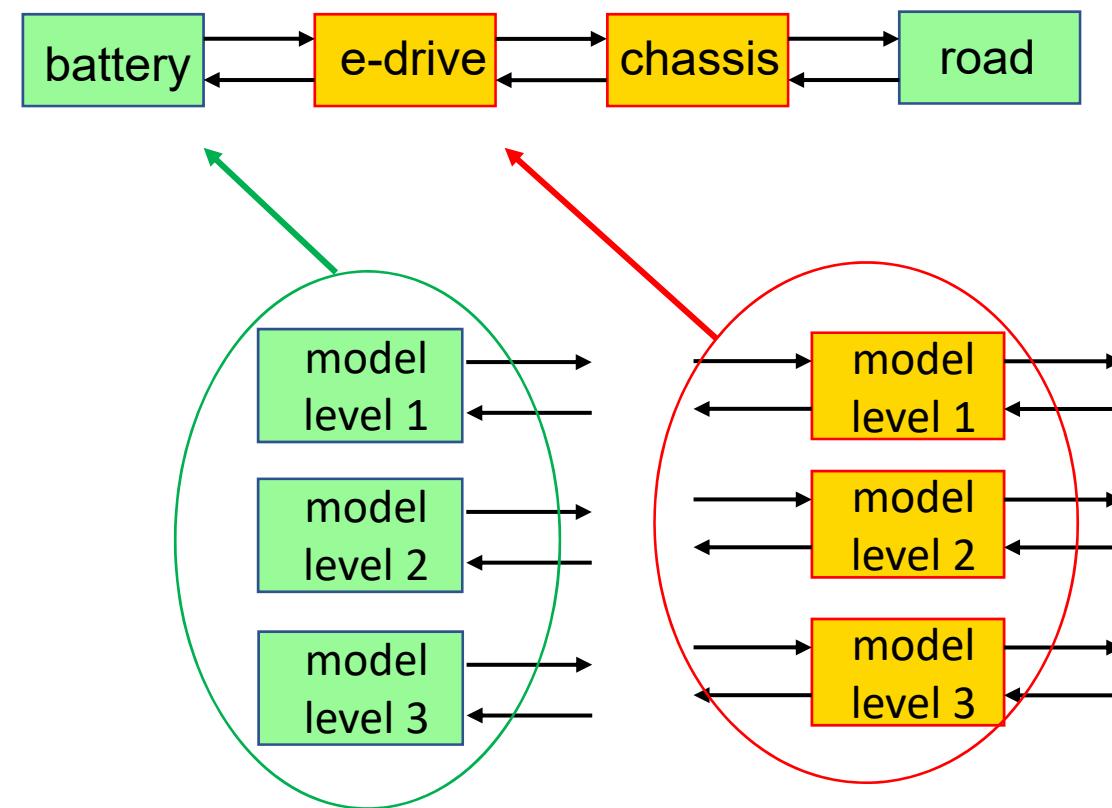


source
power
control

Multi-level modelling simulation



EMR library in
Simcenter
Amesim ©

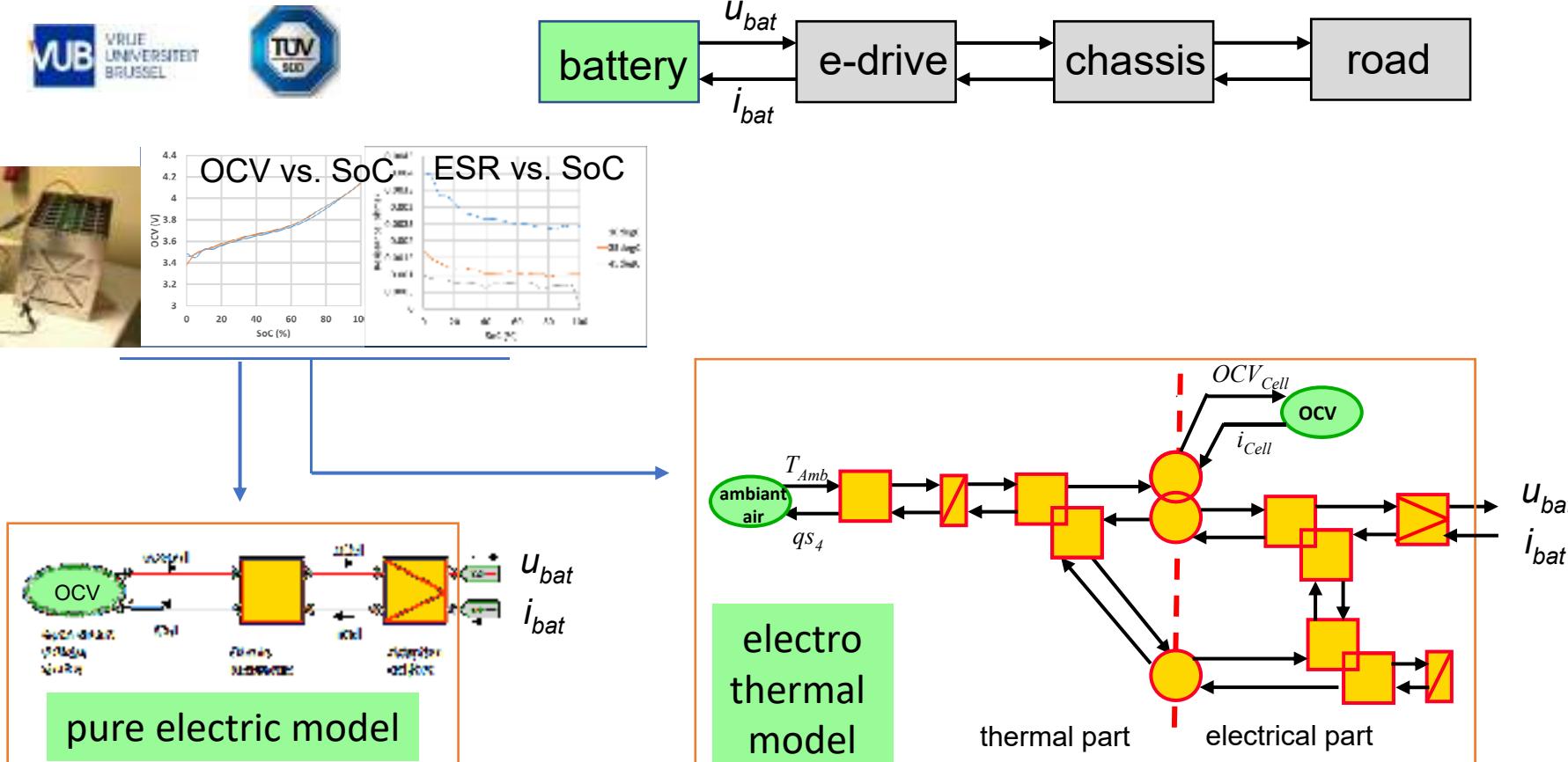


⌚ Different models can be
interchanged by “plug & play”



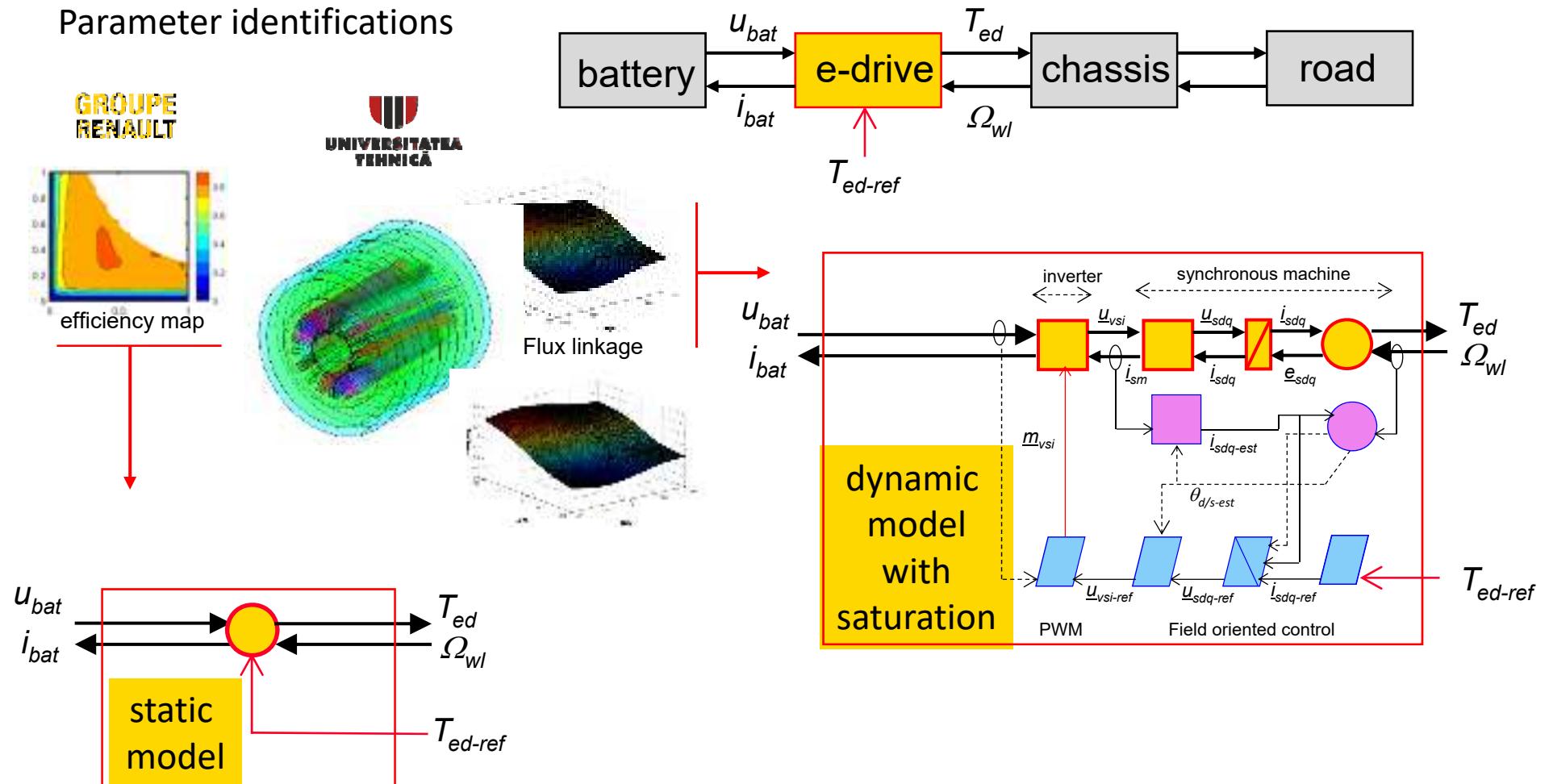
Different level of battery models

Model identifications



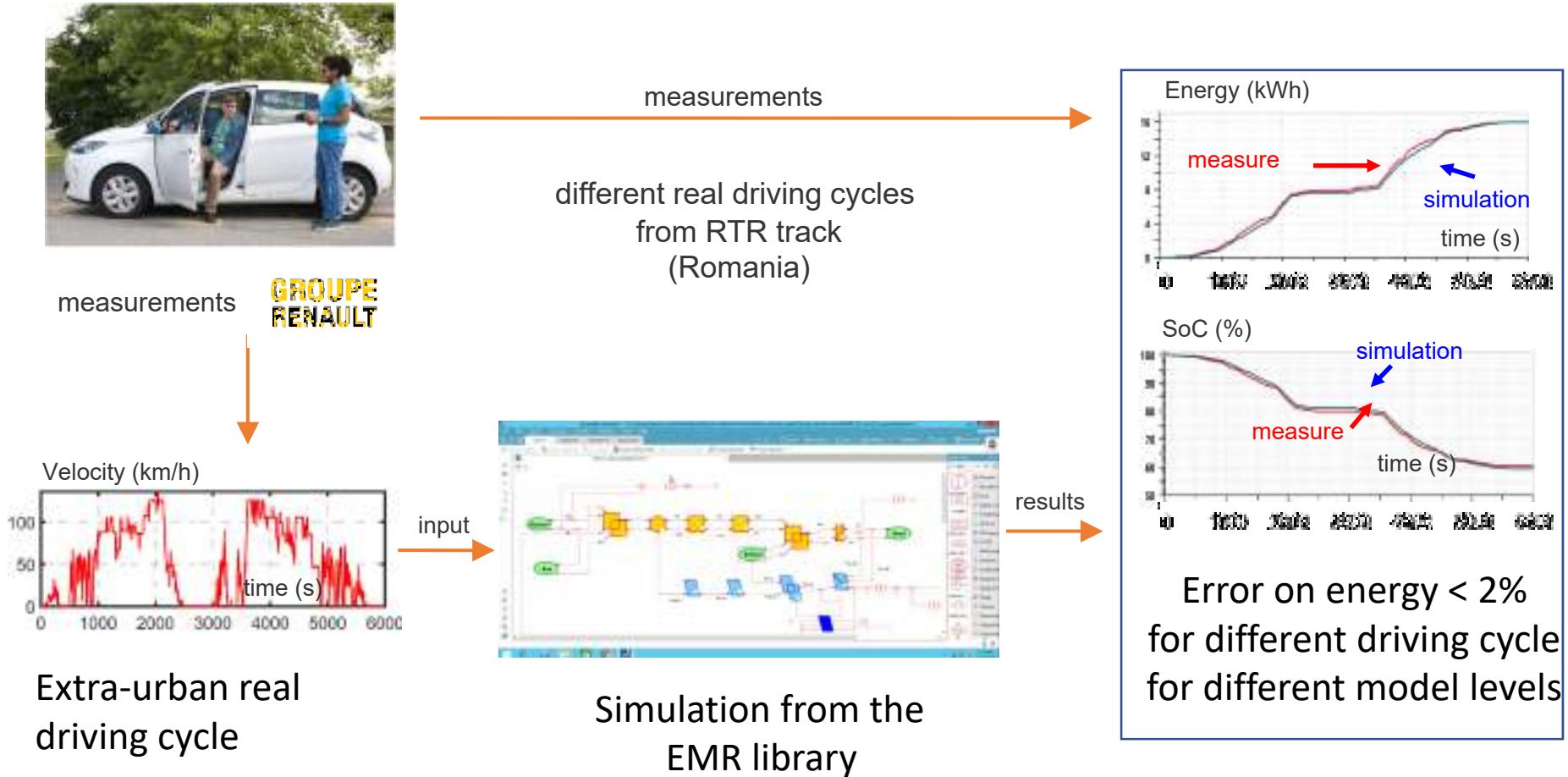
Always same Inputs / Outputs

Different level of e-drive models



Always same Inputs / Outputs

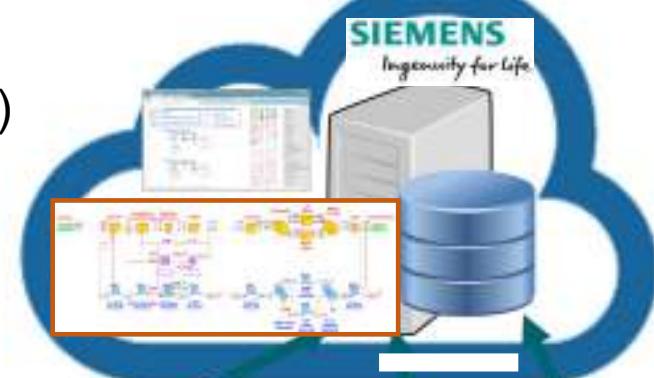
Validation of the simulation model



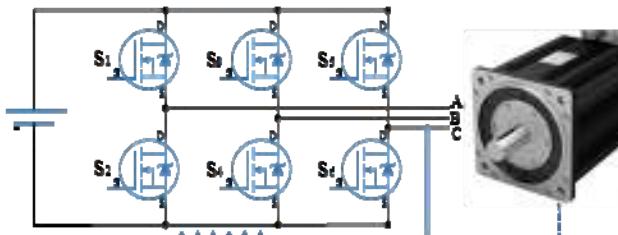
HIL testing of e-drive: principle



(PANDA Cloud)



Real e-drive
under test

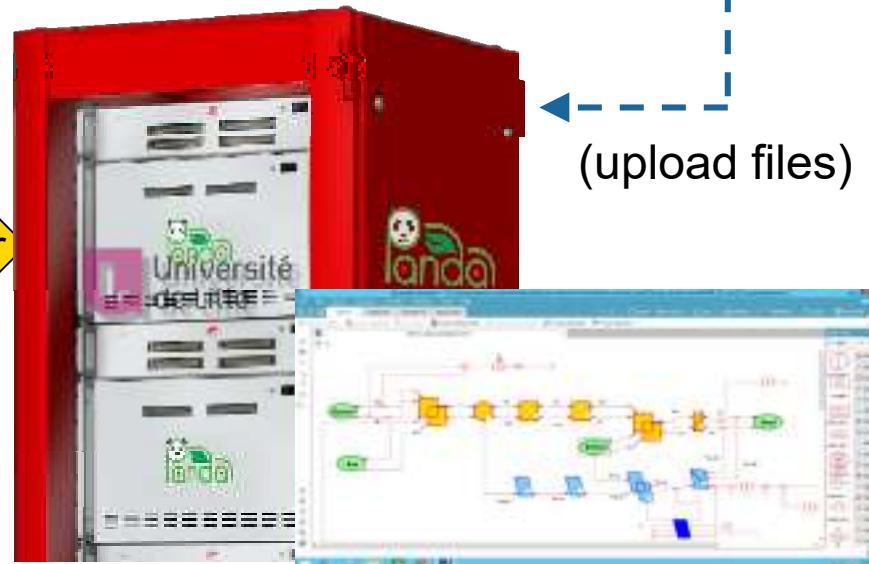


power

Power interface
& real-time simulator

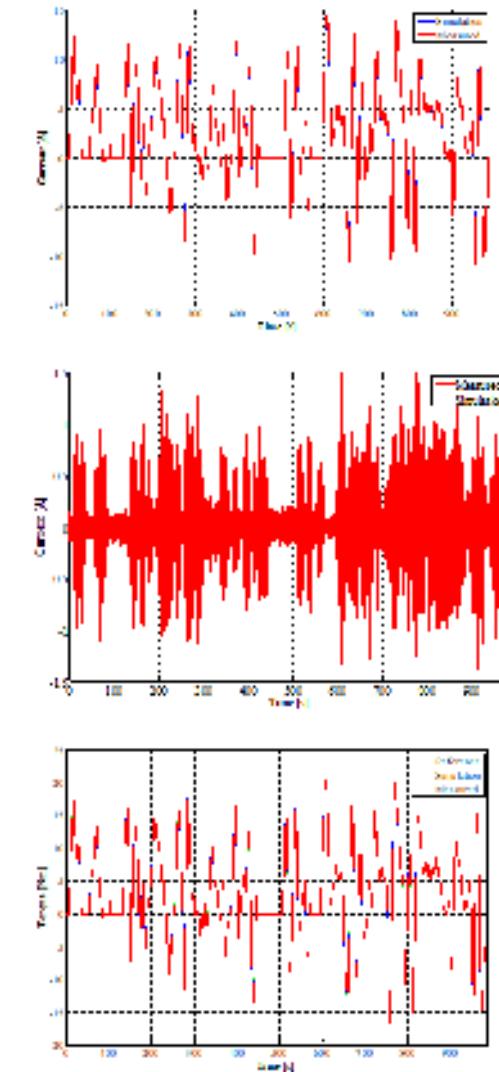
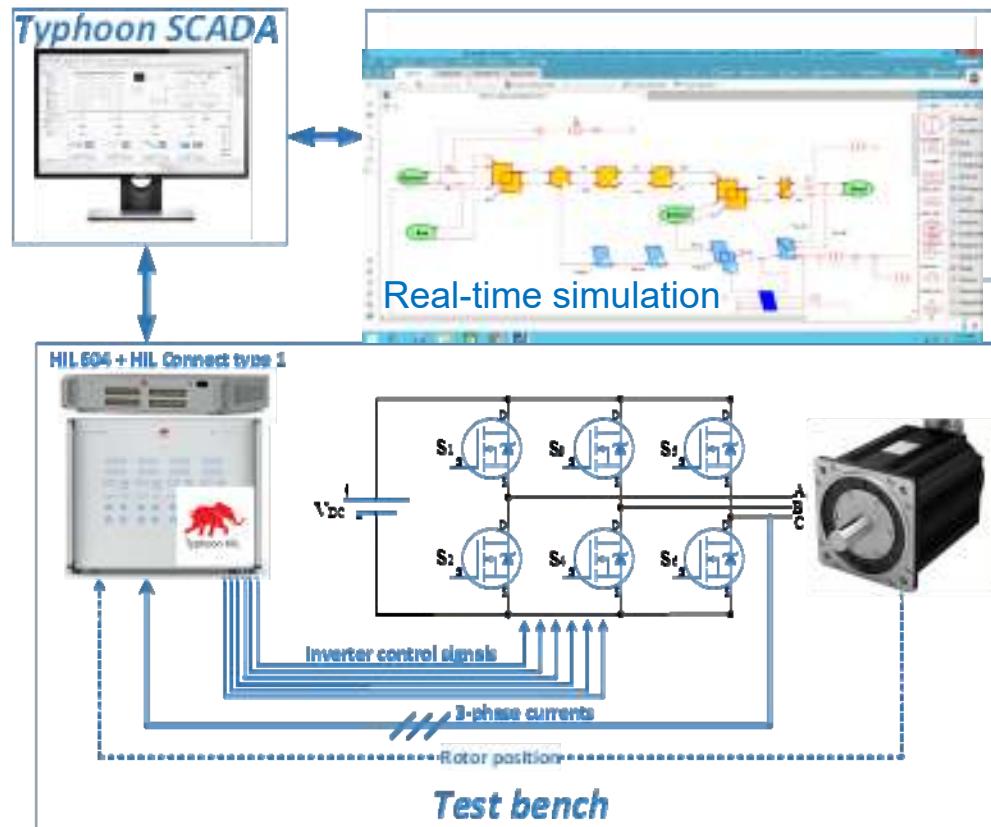


(upload files)



Real-time simulation of Renault Zoé

HIL testing of e-drive: results



experimental results



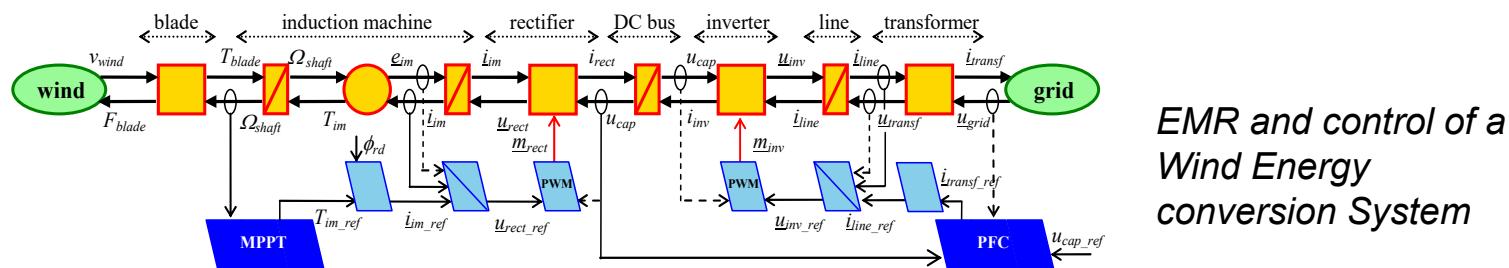
Conclusion



It's finished!

Conclusion

- Energy Conversion Systems are key points for sustainable development
- Innovative energy conversion systems must be developed
- EMR can be a way for a systematic control organization of energy conversion systems



*EMR and control of a
Wind Energy
conversion System*

Next international annual
EMR Summer School
Sion (Switzerland)
20-23 June 2022



EMR'19 summer school, Lille June 2019

Our PANDA
Thanks you for your attention !



H2020 PANDA project
<https://project-panda.eu/>

EMR formalism
<http://www.emrwebsite.org/>

Selected references

- [Bouscayrol 2000] A. Bouscayrol, B. Davat, B. de Fornel, B. François, J. P. Hautier, F. Meibody-Tabar, M. Pietrzak-David, "Multimachine Multiconverter System: application for electromechanical drives", *European Physics Journal - Applied Physics*, vol. 10, no. 2, May 2000, pp. 131-147 (common paper GREEN Nancy, L2EP Lille and LEEI Toulouse, according to the SMM project of the GDR-SDSE).
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- [Hautier 2004] J.P. Hautier, P.J. Barre, "The causal ordering graph – A tool for modelling and control law synthesis", *Studies in Informatics and Control Journal*, Vol. 13, no. 4, pp. 265-283, December 2004..
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