Final Event 24-25<sup>th</sup> of May 2022

Demos



Powerful Advanced N-Level Digital Architecture for models of electrified vehicles and their components

# **VEEM P-HEV Validation**

Robin Vincent Valeo EEM



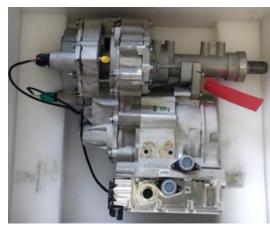


# Valeo HEV's e-drive presentation



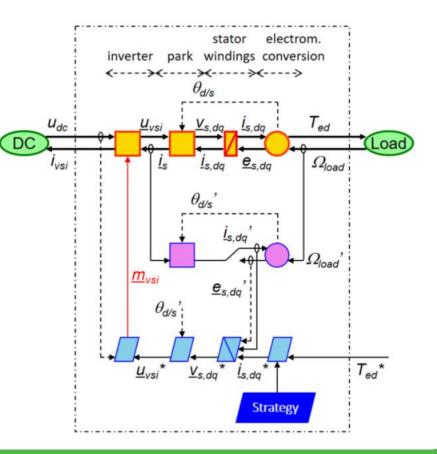
#### e-drive = Permanent Magnets Synchronous Machine (PMSM) + Inverter

- **Valeo Physical rear e-drive:**
- 25kW peak power
- Low voltage 48V
- Watercooled



#### Models:

- EMR approach to interface with other system models
- Various modelization types:
  - Open models (e.g: knowledge models)
  - Blackbox (e.g: behavior models):
    - Cloud usable: OK
    - HiL usable: KO





## Democar Vehicle presentation



Base vehicle: Peugeot 308 130ch

#### **Democar:**

- Front e-drive: iBSG 4kW
- Rear e-drive:
  - GMG 25kW
  - ratio 18 with disconnect
- Battery: 4.8kWh 48V







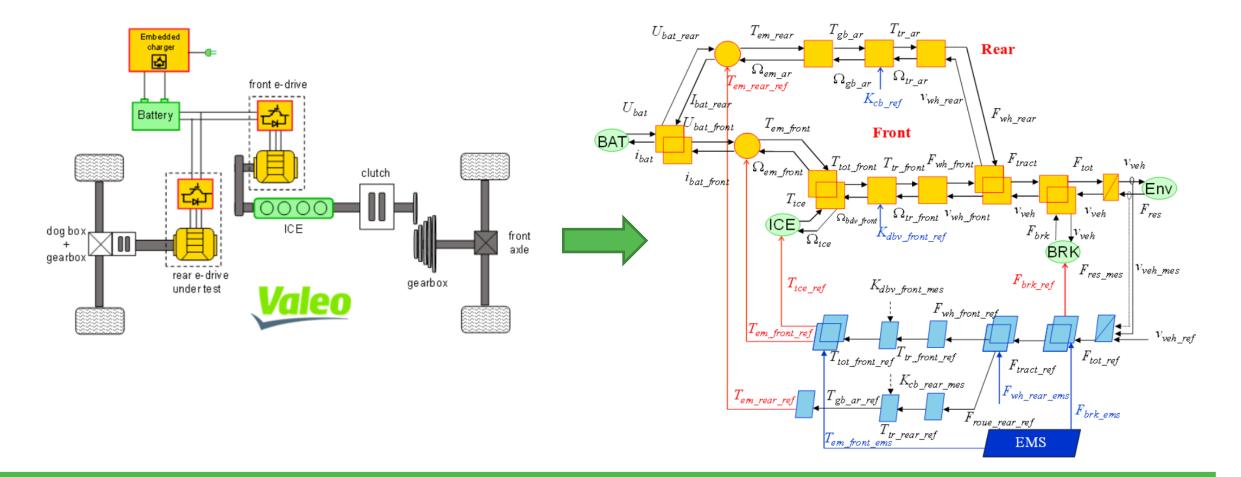


## Democar Model presentation



**Democar powertrain architecture:** 

**Vehicle model using EMR formalism:** 

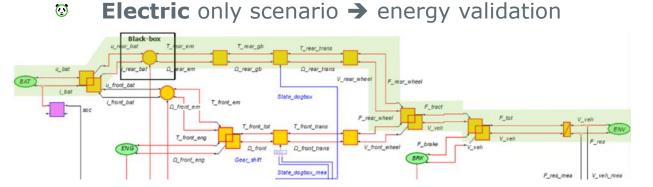




## Democar Tests presentation



#### 2 separate validations scenarii



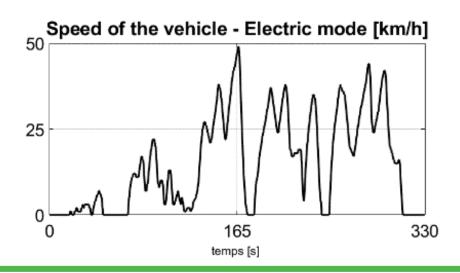
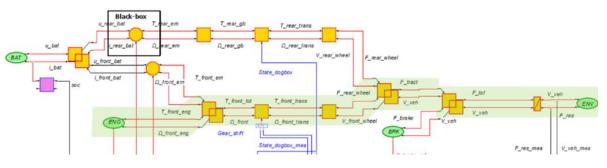
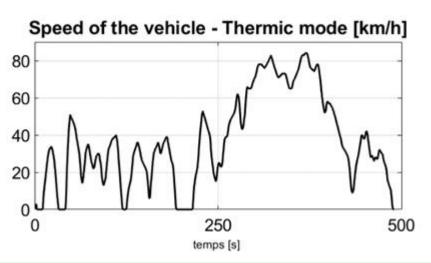


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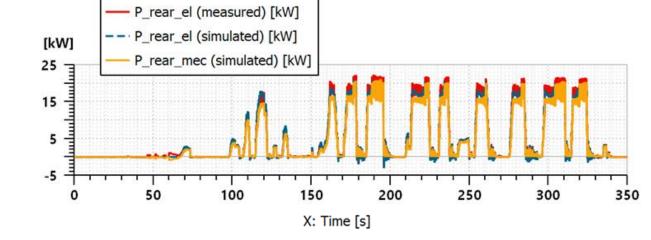
# Electric drive scenario

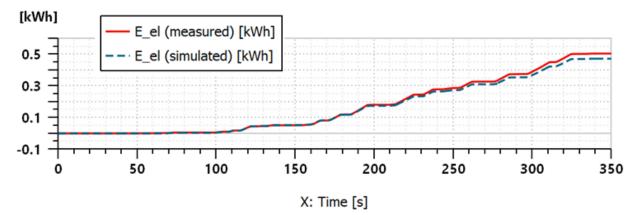
### **Electric power:**

• The electric power supplied by the eMachine in the model matches the measurement

#### So Energy:

- The cumulative energy consumption shows an error of 6.4%
- This error is constant through the cycle, demonstrating a consistent behavior





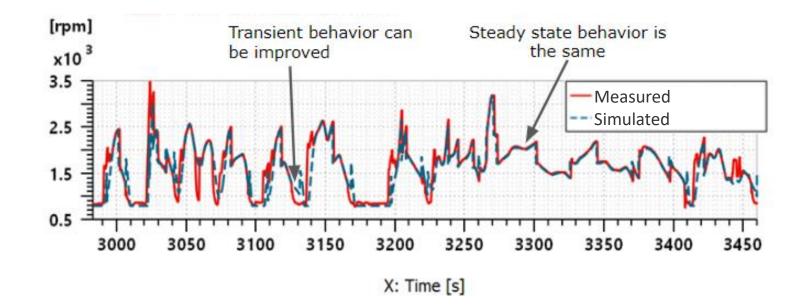




# Thermal only scenario



**Engine speed validation:** 



- Same behavior in terms of engine speed, except during transients (take-off, stop phases).
- This could be improved with a more advanced gearbox and torque converter models.



# P-HEV validation conclusion



- ☺ Good correlation in pure electric and pure thermal drive.
- **We can assume that when using both together the correlation will stay valid**.





# End of presentation

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